

APPLICATION

FOR

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TITLE: **MEASURING COUPLING CHARACTERISTICS
OF OPTICAL DEVICES**

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MEASURING COUPLING CHARACTERISTICS OF OPTICAL DEVICES

Background

This invention relates generally to determining coupling characteristics of optical devices.

A 2 x 2 optical device is an optical device that
5 receives at least two inputs and provides at least two outputs. Examples of such devices include couplers, and Michelson and Mach-Zehnder interferometers.

It may be desired to measure the effective coupling coefficient of optical devices. The coupling coefficient
10 indicates how much of the input light is coupled to the output port. The coupling coefficient may be measured by providing a light source to a first input port of the 2 x 2 optical device and a detector to a first output port of the 2 x 2 optical device. Thus, the first input and output
15 ports are tested and then the light source and detector are decoupled from those ports and recoupled to the second input and output ports of the 2 x 2 optical device.

In traditional measurement systems, after measuring the output power at one of two output ports, the power
20 detector is disconnected and reconnected to the other output port. During this process, the input power can be changed slightly due to a power fluctuation that depends on the light source used. Since connectors are now connected and reconnected, the insertion loss may vary as a result of

the mechanical disturbance arising from changing the connectors. This insertion loss variation, as well as other sources of loss in the measurement system, may limit the accuracy of the coupling coefficient measurement. For
5 example, when the coupling ratio is estimated from the ratio of the two output powers, variations in the losses of the two output connectors contribute to measurement error. The power fluctuation can be avoided using two-detector measurement systems; however, the variation in connector
10 losses still exists.

Thus, there is a need for better ways to measure coupling characteristics of optical devices.

Brief Description of the Drawings

15 Figure 1 is a schematic depiction of one embodiment of the present invention;

Figure 2 is a depiction of coupling ratio versus wavelength for a prototype embodiment of the present invention;

20 Figure 3 is a depiction of one embodiment of the present invention illustrating the contributions to measurement error;

Figure 4 is a schematic depiction of another embodiment of the present invention; and

25 Figure 5 is a depiction of coupling ratio versus wavelength.

Detailed Description

Referring to Figure 1, a light source 14 may be coupled to a 2 x 2 optical device 12 through a 1 x 2 optical switch 16. Connectors 18a and 18b may be provided
5 to couple the optical switch 16 to the 2 x 2 optical device 12. However, once the connections are made between the switch 16 and the device 12, they need not be undone until after the completion of the test.

Similarly, a pair of detectors 22 may be coupled by
10 connectors 20a and 20b to the outputs of the 2 x 2 optical device 12. Again, it is not necessary to disconnect the detector during the course of any testing.

The arrangement shown in Figure 1 may reduce measurement errors caused either by light source power
15 fluctuations or by the variation of insertion losses. In some embodiments, input power variation and connector loss statistical errors may be reduced, measurement repeatability may be increased, and data may be obtained more independently of variation in insertion losses. In
20 some embodiments, this may result in an order of magnitude decrease in measurement errors.

For example, referring to Figure 2, a typical standard deviation of ± 0.013 is obtained for the coupling ratio data for couplers measured with traditional systems.
25 However, using the system shown in Figure 1, the standard deviation in repeated coupling ratio measurements on the

same device is reduced to ± 0.0015 in one embodiment.
 Thus, the two devices shown in Fig. 2 would be practically indistinguishable using a traditional measurement, but are easily distinguished using the method disclosed here.

5 The coupling ratio of a 2 x 2 loss-less device can be parameterized with an effective cross-transfer (from input A to output D or from input B to output C of the device 12 in Figure 1) coupling ratio T. For loss-less coupling devices, the direct-transfer (from input A to output C or
 10 from input B to output D) coupling ratio is 1-T.

 The fraction of optical power transmitted to the coupling region (or from the coupling region to) port i can be parameterized by T_i (where i is either the input port A or B or the output port C or D), the overall fraction of
 15 power transferred from:

input A to output C: $T_{AC} = T_A(1-T)T_C$ input A to output D: $T_{AD} = T_ATT_D$
 input B to output C: $T_{BC} = T_BT_TT_C$ input B to output D: $T_{BD} = T_B(1-T)T_D$

20 If there are no mechanical disturbances and no input power fluctuations during the input and output power measurements, then T_i 's (i = A, B, C, and D) are constant. T_i includes the input/output insertion losses and waveguide propagation losses, which can be different for different
 25 polarization states of light. It can then be shown that:

$$T = 1 / (1 + ((T_{AC}/T_{AD}) / (T_{BC}/T_{BD}))^{0.5}) \quad (1)$$

It turns out that T calculated from Eq. (1) is independent of the overall input insertion losses T_i ($i = A, B, C, \text{ and } D$) so long as they are not changed during each measurement.

5 For 2×2 devices, it is convenient to define a parameter $\Delta = 10 \times \log ((1-T)/T)$, which measures the deviation from the ideal 3-dB (50/50) coupler of $T = 0.5$ ($\Delta = 0$). For output powers, P_{AC} , P_{AD} , P_{BC} , and P_{BD} measured in dBm, Δ is then:

10

$$\Delta = 0.5 \times (P_{AC}(\text{dBm}) - P_{AD}(\text{dBm}) - (P_{BC}(\text{dBm}) - P_{BD}(\text{dBm}))) \quad (2)$$

In essence, four measurements, rather than two, are made. And coupling ratio T is calculated using Eq. (1) or
15 Eq. (2). Using this algorithm and method, the variations in connector losses (related to T_i 's) may be theoretically eliminated since they do not appear in these equations.

In this two-detector measurement system, two power detectors 22, and a 1 by 2 optical switch 16 are used.
20 This measurement system can reduce errors associated with power fluctuation and those associated with mechanical disturbance or with unknown losses in the device or measurement system. The power fluctuation errors in this measurement system are reduced since the two output powers
25 are measured simultaneously using two power detectors 22 and their ratio is used in Eq. (1). The mechanical

disturbance is reduced by using two detectors 22 and a 1 x 2 optical switch 16. Mechanical disturbance may be reduced during the four T_{ij} ($ij = AC, AD, BC, \text{ and } BD$) measurements since no connections need be disconnected and reconnected
5 (connector change for switching input light from port A to port B using 1 x 2 optical switch has minimum mechanical disturbance). While improving the ease of the measurement, the use of a 1 x 2 switch is not necessary in order to realize the benefits of the improved methods described
10 here. Advantageously, the losses in the system, described by T_i , do not change during the course of a single measurement so that their effect is reduced or eliminated by the procedure described above and summarized in Eqs. (1) and (2). Therefore, it is acceptable to physically connect
15 and disconnect the two inputs between the two measurements described above. Thus, in cases where a switch is not available, manual connections of the inputs can be used with no loss in accuracy.

The data obtained using these techniques demonstrate
20 that the illustrated two-detector-measurement system may reduce measurement errors by an order of magnitude in some cases. Since T estimated from Eq. (1) is independent of the power of input light and the overall insertion losses of the two input and two output ports, any light source can
25 be used without demanding high quality optical connectors.

Since the powers measured on the two output ports for light input to a given input port always appear as a ratio in Eq. (1), the two power detectors 22 need not necessarily have the same power calibration as long as their optical
5 responses are in the linear region. Lastly, this measurement method can be extended for measuring the coupling coefficients of $n \times n$ optical devices using $1 \times n$ optical switch and n detectors.

Referring to Figure 2, two devices are depicted on a
10 graph of wavelength versus coupling ratio. These devices were designed to have the same coupling ratio by their manufacturer, yet using the apparatus shown in Figure 1, it can be determined that, actually, the coupling ratios of the two devices are quite different. The high resolution
15 is due to the insensitivity to losses and light source power variations, enabling smaller coupling ratio differences to be detected.

The coupling characteristics of many integrated optical devices are polarization sensitive, *i.e.*, their
20 coupling ratios may depend on the input polarization state. In many cases, the polarization state of the light present in optical systems is neither controlled nor stable, and many devices are designed to minimize their polarization dependence. In general, polarization dependence is an
25 important property of most optical devices and therefore it is important to be able to accurately measure it in order

to determine its effects in optical systems. The measurement method described above may be extended in order to determine the polarization dependence of the coupling coefficient of optical devices.

5 The measurement system shown in Figure 4 includes a polarization controller 26 and two photo detectors 22. The polarization controller 26 is placed in between a laser source 24, optical switch 16, and device under test (DUT) 12. For measuring wavelength dependent coupling, either a
10 wavelength tunable or broadband source may be used. The light power from the two coupled outputs is then directed to two photo detectors 22 simultaneously. In the case of a broadband source, an optical spectrum analyzer or tunable optical filter may be used at the detectors in order to
15 measure wavelength dependence. With the source connected to input #1, the polarization dependent transmission through the device is measured by any one of several methods known in the art, e.g., the four-state Mueller method or direct polarization scanning or scrambling
20 methods. In the Mueller method, four well-defined Mueller polarization states are generated by the controller 26 and the output signals are measured and recorded for each state. The source 24 is then switched to input #2 for the same polarization scans, without moving the output
25 alignment. For wavelength-dependent measurements, one of several methods may be used - the wavelength may be scanned

for each polarization state, the polarization states may be scanned for each wavelength, or both wavelength and polarization may be scanned simultaneously and asynchronously. The data (16 data points for a fixed
5 wavelength measurement) collected from two detectors 22 for the two polarization scans are used to compute the polarization dependent coupling ratio (Δ) of the intrinsic device under test 12.

The minimum (T_{min}) and maximum (T_{max}) coupling ratios
10 are computed from one of the polarization dependence measurements described above. For example, Mueller data from each output for input #1 and input #2 are measured independently as indicated in Figure 3. Referring to Fig. 3, α_i and β_i represent the insertion losses from coupling the
15 device to the source and detectors, respectively, L_i represents the propagation losses in the waveguide regions indicated in Fig. 3, X is the coupling ratio in the coupler, and B is the fraction of power that remains uncoupled (equal to $1-X$ for no loss in the coupling
20 region). In many cases, the device under test 12 exhibits birefringence. In planar optical devices, the birefringence has axes typically either parallel (TE) or perpendicular (TM) to the wafer surface. Therefore, T_{min} and T_{max} generally correspond to TE and TM polarization
25 states. It is also known that the losses in the waveguide are TE and TM mode dependent, and waveguide bend and

coupling are usually in-plane on a planar lightwave circuit chip. Therefore, the 2 x 2 transfer matrices for both B and X as well as waveguide bend loss $L_i (i=1,2,3,4)$ are typically diagonal in TE and TM modes, i.e., there is no change in polarization state during propagation through the device, and the loss and coupling axes are typically parallel to each other. Under these conditions, T_{max} polarization on the output 1 corresponds to the T_{min} polarization at the output 2 and vice versa. Combining these results, we can extract the polarization dependent coupling ratio of the intrinsic device. From Figure 3 we can see the output 1 and output 2 powers are proportional to input power:

$$\begin{aligned}
 O_1 &= I_0 \alpha_1 L_1 B L_3 \beta_1 & O'_1 &= I_0 \alpha_2 L_2 X L_3 \beta_1 \\
 O_2 &= I_0 \alpha_1 L_1 X L_4 \beta_2 & O'_2 &= I_0 \alpha_2 L_2 B L_4 \beta_2
 \end{aligned}$$

O_i and O'_i are the output powers corresponding to the source connected to input 1 and input 2, respectively. From these equations, we can compute the maximum and minimum effective coupling ratios as:

$$\Delta_{\max} \equiv 10 \log \left(\frac{B_{\max}}{X_{\min}} \right) = 5 \log \left(\frac{O_{1,\max} O'_{2,\max}}{O_{2,\min} O'_{1,\min}} \right)$$

$$\Delta_{\min} \equiv 10 \log \left(\frac{B_{\min}}{X_{\max}} \right) = 5 \log \left(\frac{O_{1,\min} O'_{2,\min}}{O_{2,\max} O'_{1,\max}} \right)$$

where the maximum and minimum of the output may be computed from the four Mueller states or by some other means as known in the art. Note that this definition of Δ corresponds to $\Delta < 0$ for over-coupling, $\Delta > 0$ for under-coupling, and $\Delta = 0$ for equal (50/50) coupling. Other conventions for Δ may be used without loss of generality of the conclusions. Note also that, under the conditions assumed above (*i.e.*, the axes of the polarization dependent losses and polarization dependent coupling are parallel and no cross coupling of polarization states occurs), the polarization dependent loss from the input and output waveguide is canceled, as well as the fiber to the waveguide loss. In this way we obtain the true intrinsic coupling of the symmetric device. Since the TM mode is normally wider due to waveguide stress, the TM mode is slightly more coupled than the TE mode:

$$\Delta_{TE} \equiv 10 \log \left(\frac{B_{\max}}{X_{\min}} \right) = 5 \log \left(\frac{O_{1,\max} O'_{2,\max}}{O_{2,\min} O'_{1,\min}} \right)$$

$$\Delta_{TM} \equiv 10 \log \left(\frac{B_{\min}}{X_{\max}} \right) = 5 \log \left(\frac{O_{1,\min} O'_{2,\min}}{O_{2,\max} O'_{1,\max}} \right)$$

From the above formula, the intrinsic coupling ratio can be measured, at least partially, if not completely, removed from the error from polarization dependent coupling, fiber alignment uncertainty, and the polarization dependent losses from the waveguide that leads to and from the intrinsic device.

Figure 5 shows a graph of coupling ratio versus wavelength measured by the technique described herein. For this device, the polarization dependent coupling ratio has a difference as large as 0.7dB between the minimum and the maximum or the TE and TM modes. The random polarization light source can give any value in between the upper line and the lower line for coupling ratio, even if the other error sources have been eliminated. The coupling ratio is increasingly over coupled with the increase of wavelength due to the reduced confinement of the mode at longer wavelengths.

While the present invention has been described with respect to a limited number of embodiments, those skilled in the art will appreciate numerous modifications and variations therefrom. It is intended that the appended claims cover all such modifications and variations as fall within the true spirit and scope of this present invention.

What is claimed is: